

Spline estimator and its asymptotic properties in multiresponse nonparametric regression model

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15
Spline estimator and its asymptotic properties
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Abstract

In applications, we often meet the problem where more than one response variable is observed at several values of predictor variables, and these responses are correlated with each other. The multiresponse nonparametric regression model approach is appropriate to model the functions which represent relationship between response and predictor variables. This relationship is drawn by the regression function. The principal problem of this model approach is estimating of the regression function of this model. The spline estimator is one of the most popular estimators used for estimating it. In this paper we discuss methods to obtain a smoothing spline estimator for estimating the regression function, to get a covariance matrix estimator, and to choose an optimum smoothing parameter. In addition, we investigate the asymptotic properties of the smoothing spline estimator.

Keywords: multiresponse nonparametric regression, covariance matrix, spline estimator, smoothing parameter, asymptotic properties

1. Introduction

1
Statistical analysis often involves building mathematical models which examine association between response and predictor variables. Spline smoothing is a general class of powerful and flexible modeling techniques. Research on smoothing spline models has attracted a great deal of attention in recent years, and the methodology has been widely used in many areas. Smoothing spline estimator with its powerful and flexible properties is one of the most popular estimators used for estimating regression function of the nonparametric regression model. Several types of spline estimator have been

considered by researchers to estimate the regression function. Original spline was used to estimate the regression function for smooth data by Kimeldorf and Wahba (1971), Craven and Wahba (1979), and Wahba (1990). M-type spline was proposed by Cox (1983), and Cox and O'Sullivan (1996) to overcome outliers in nonparametric regression. Construction of confidence interval for original spline model has been provided by Wahba (1983). A comparison between generalized cross validation and generalized maximum likelihood for choosing a smoothing parameter in the generalized spline smoothing problem was presented by Wahba (1985). Relaxed spline and quantile spline were introduced by Oehlert (1992), and Koenker, Pin, and Portnoy (1994), respectively. Smoothing spline for the case of correlated errors was discussed by Wang (1998). Reproducing kernel Hilbert spaces (RKHS) concept has been used by

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Wahba (2000) to build spline statistical model. Lee (2004) combined smoothing spline estimates of different smoothness to form a final improved estimate. Cardot, Crambes, Kneip, and Sarda (2007) investigated the asymptotic property of smoothing splines in functional linear regression with errors-in-variables. Liu, Tong, and Wang (2007) have discussed smoothing spline estimator for variance functions. Aydin (2007) compared goodness of spline and kernel in estimating nonparametric regression model for gross national product data. Aydin, Memmedhi, and Omay (2013) have studied the determination of an optimum smoothing parameter for nonparametric regression using smoothing spline. But, researchers mentioned above just discussed spline estimators for estimating regression function of single response nonparametric regression models. It means that they have not discussed spline estimators in the multiresponse nonparametric regression model.

In many real cases, we often find cases where more than one response variable is observed at several values of predictor variables, and there are correlations between the response and each other. Multiresponse nonparametric regression model provides potential methods to model the functions that represent the relationship of these variables. Some researchers have discussed estimating methods in the multiresponse nonparametric models. Wegman (1981), Miller and Wegman (1987), and Flessler (1991) provided spline smoothing algorithms. Wahba (1992) used RKHS method to develop the theory of general smoothing splines. Gooijer, Gannoun, and Larramendy (1999), and Fernandez and Opsomer (2005) proposed methods to estimate nonparametric regression models with serially and spatially correlated errors, respectively. Wang, Guo, and Brown (2000) used spline smoothing for estimating biresponse nonparametric regression model with the same correlation of errors. Lestari, Budiantara, Sunaryo, and Mashuri (2009), and Lestari, Budiantara, Sunaryo, and Mashuri (2010) used spline to estimate the multiresponse nonparametric regression model in cases of equal correlation of errors and unequal correlation of errors, respectively. Chamidah, Budiantara, Sunaryo, and Zain (2012) applied the multiresponse nonparametric regression model to design child growth chart. Lestari, Budiantara, Sunaryo, and Mashuri (2012) have studied spline to estimate the heteroscedastic multiresponse nonparametric regression model. Chamidah and Lestari (2016) discussed estimation of the homoscedastic multiresponse nonparametric regression model when the numbers of observations were unbalanced. Lestari, Fatmawati, and Budiantara (2017) estimated smoothing spline in the multiresponse nonparametric regression model by using RKHS method. Lestari, Fatmawati, Budiantara, and Chamidah (2018), and Lestari, Fatmawati, Budiantara, and Chamidah (2019) estimated regression functions and smoothing parameters using spline and kernel estimators. Yet, all these researchers assumed that the covariance matrix was known. When it is unknown, it has to be estimated from the data and it can affect the estimates of the smoothing parameters (Wang, 1998). Also, these researchers have not discussed the estimation of optimum smoothing parameter in the multiresponse nonparametric regression model when the variances of errors are not the same. In addition, none of these researchers have discussed the asymptotic properties of the spline estimator.

In nonparametric regression, we often consider asymptotic properties of estimator based on certain goodness

criteria. In regression nonparametric analysis, investigating of the asymptotic properties of an estimator is an important step for obtaining convergence rate of regression function estimator. There are some criteria which have often been used by researchers to determine goodness of spline estimator approach. Eubank (1988) proposed the mean square error criterion. Speckman (1985), and Carter, Eagleson, and Silverman (1994) have studied minimax criterion, while Cox (1983) and Cox and O'Sullivan (1996) considered the mean square error criterion for M-type spline approach. Eggermont, Eubank, and LaRiccia (2010) have studied convergence rate of spline estimator in the varying coefficient model. Li and Zhang (2010) established strong consistency and asymptotic normality of penalized spline in the varying-coefficient single-index model. Wang (2012) constructed the M-type estimator of regression function and has studied its asymptotic normality property. Ping and Lin (2013) discussed the asymptotic properties of spline estimator in the partly linear model for longitudinal data. Chen and Christensen (2015) have studied both asymptotic properties and convergence rate of some estimators in the nonparametric model. Although, these researchers have discussed some asymptotic properties of some estimators, they discussed the asymptotic properties in single response nonparametric regression models only. They have not discussed the asymptotic properties in multiresponse nonparametric regression models.

In this paper, we develop the biresponse nonparametric regression model proposed by Wang *et al.* (2000) to the more general model, i.e., the multiresponse nonparametric regression model. Note that we need the covariance matrix to determine a weight matrix that will be used in the optimization penalized weighted least-square (PWLS) to obtain a smoothing spline estimator which depends on the smoothing parameter to estimate regression function of the model. Therefore, in this paper we discuss methods to obtain the smoothing spline estimator, to get the covariance matrix estimator, and to choose the optimum smoothing parameter. We also investigate the asymptotic properties of smoothing spline estimators of the multiresponse nonparametric regression model based on integrated mean square error (IMSE) criterion.

2. Methods

Firstly, we consider data (y_{ki}, t_{ki}) , $k=1,2,\dots,p$; $i=1,2,\dots,n_k$ that follow the multiresponse nonparametric regression model as follows:

$$y_{ki} = f_k(t_{ki}) + \varepsilon_{ki} \quad (1)$$

where f_1, f_2, \dots, f_p are unknown regression functions assumed to be smoothed and contained in Sobolev space $W_2^m[a_k, b_k]$.

ε_{ki} are zero-mean independent random errors with variance σ_{ki}^2 . Based on (1), we can determine the covariance matrix of errors. The estimated multiresponse nonparametric regression model based on smoothing spline estimator can be obtained by carrying out optimization PWLS:

$$\begin{aligned} \text{Min}_{f_1, f_2, \dots, f_p \in W_2} \{ & (\sum_{k=1}^p n_k)^{-1} (y_1 - f_1)' W_1(\sigma_1^2) (y_1 - f_1) + \dots + (y_p - f_p)' W_p(\sigma_p^2) (y_p - f_p) + \\ & \lambda_1 \int_{a_1}^{b_1} (f_1^{(2)}(t))^2 dt + \dots + \lambda_p \int_{a_p}^{b_p} (f_p^{(2)}(t))^2 dt \} \end{aligned} \quad (2)$$

Then, to get the solution of optimization PWLS in (2), we use RKHS method. Secondly, we estimate the covariance matrix of errors using maximum likelihood method, and estimate the optimum smoothing parameter based on the minimum value of generalized cross-validation (GCV). Finally, we determine the asymptotic properties of the smoothing spline estimator of regression function based on IMSE criterion.

3. Results and Discussion

Suppose that $\underline{y} = (y_1, y_2, \dots, y_p)'$, $\underline{f} = (f_1, f_2, \dots, f_p)'$, $\underline{\varepsilon} = (\varepsilon_1, \varepsilon_2, \dots, \varepsilon_p)'$, and $\underline{t} = (t_1, t_2, \dots, t_p)'$ where $\underline{y}_{k1} = (y_{k1}, y_{k2}, \dots, y_{kn_k})'$, $\underline{f}_k = (f_k(t_{k1}), f_k(t_{k2}), \dots, f_k(t_{kn_k}))'$, $\underline{\varepsilon}_k = (\varepsilon_{k1}, \varepsilon_{k2}, \dots, \varepsilon_{kn_k})'$, $\underline{t}_k = (t_{k1}, t_{k2}, \dots, t_{kn_k})'$, $k = 1, 2, \dots, p$; $i = 1, 2, \dots, n_k$. Therefore, the model (1) can be written in the following matrix notation:

$$\underline{y} = \underline{f} + \underline{\varepsilon} \quad (3)$$

where $E(\underline{\varepsilon}) = \underline{0}$, and namely $Cov(\underline{\varepsilon}) = [W(\sigma^2)]^{-1}$.

3.1 Covariance matrix of random errors

The following theorem gives us how we determine the covariance matrix of random errors, $Cov(\underline{\varepsilon}) = [W(\sigma^2)]^{-1}$, in the multiresponse nonparametric regression model.

Theorem 1. Suppose that the data set (y_{ki}, t_{ki}) , $k = 1, 2, \dots, p$; $i = 1, 2, \dots, n_k$ follows the multiresponse nonparametric regression model given in (1):

$$y_{ki} = f_k(t_{ki}) + \varepsilon_{ki}$$

If $[W(\sigma^2)]^{-1}$ denotes the covariance matrix of errors, then

$$[W(\sigma^2)]^{-1} = \text{diag}(W_1(\sigma_1^2), W_2(\sigma_2^2), \dots, W_p(\sigma_p^2))$$

where matrix $W_k(\sigma_k^2)$ is given by:

$$W_k(\sigma_k^2) = \begin{bmatrix} \sigma_{k1}^2 & \sigma_{k(1,2)} & \dots & \sigma_{k(1,n_k)} \\ \sigma_{k(2,1)} & \sigma_{k2}^2 & \dots & \sigma_{k(2,n_k)} \\ \vdots & \vdots & \ddots & \vdots \\ \sigma_{k(n_k,1)} & \sigma_{k(n_k,2)} & \dots & \sigma_{kn_k}^2 \end{bmatrix}, k = 1, 2, \dots, p.$$

Proof. $Cov(\underline{\varepsilon}) = E(\underline{\varepsilon} - E(\underline{\varepsilon}))(\underline{\varepsilon} - E(\underline{\varepsilon}))'$

$$= E[(\varepsilon_{11}, \dots, \varepsilon_{1n_1}, \varepsilon_{21}, \dots, \varepsilon_{2n_2}, \dots, \varepsilon_{p1}, \dots, \varepsilon_{pn_p})'(\varepsilon_{11}, \dots, \varepsilon_{1n_1}, \varepsilon_{21}, \dots, \varepsilon_{2n_2}, \dots, \varepsilon_{p1}, \dots, \varepsilon_{pn_p})]$$

$$= \begin{bmatrix} W_{11} & W_{12} & \dots & W_{1p} \\ W_{21} & W_{22} & \dots & W_{2p} \\ \vdots & \vdots & \ddots & \vdots \\ W_{p1} & W_{p2} & \dots & W_{pp} \end{bmatrix} = [W(\sigma^2)]^{-1} \quad (4)$$

$$\text{where } W_{kl} = \begin{cases} \text{diag}(\sigma_{k1}^2, \sigma_{k2}^2, \dots, \sigma_{kn_k}^2), & k=l(k=1,2,\dots,p) \\ \text{diag}(\sigma_{(kl)1}, \sigma_{(kl)2}, \dots, \sigma_{(kl)n_k}), & k \neq l \end{cases}$$

$$\text{Since } \sigma_{kl} = \rho_{kl} \sigma_k \sigma_l \text{ and } \rho_{kl} = \begin{cases} \rho_k, & k=l \\ 0, & k \neq l \end{cases}, \text{ then we have: } W_{kl} = \begin{cases} \text{diag}(\sigma_{k1}^2, \sigma_{k2}^2, \dots, \sigma_{kn_k}^2), & k=l(k=1,2,\dots,p) \\ 0, & k \neq l \end{cases}$$

Therefore, we can write equation (4) as follows:

$$[W(\sigma^2)]^{-1} = \text{diag}(W_1(\sigma_1^2), W_2(\sigma_2^2), \dots, W_p(\sigma_p^2))$$

where matrix $W_k(\sigma_k^2)$ is given by:

$$W_k(\sigma_k^2) = \begin{bmatrix} \sigma_{k1}^2 & \sigma_{k(1,2)} & \dots & \sigma_{k(1,n_k)} \\ \sigma_{k(2,1)} & \sigma_{k2}^2 & \dots & \sigma_{k(2,n_k)} \\ \vdots & \vdots & \ddots & \vdots \\ \sigma_{k(n_k,1)} & \sigma_{k(n_k,2)} & \dots & \sigma_{kn_k}^2 \end{bmatrix}, k=1,2,\dots,p.$$

3.2 Estimation of regression function

Suppose that data set $(y_{ki}, t_{ki}), k=1,2,\dots,p, i=1,2,\dots,n_k$, follows the model given in (1). We can determine the smoothing spline estimator for regression function of the model given in (1) by solving the following PWLS:

$$\begin{aligned} \text{Min}_{f_1, f_2, \dots, f_p \in W_2^m} \{ & (\sum_{k=1}^p n_k)^{-1} (y_1 - f_1)' W_1(\sigma_1^2) (y_1 - f_1) + \dots + (y_p - f_p)' W_p(\sigma_p^2) (y_p - f_p) + \\ & \lambda_1 \int_{a_1}^{b_1} (f_1^{(2)}(t))^2 dt + \dots + \lambda_p \int_{a_p}^{b_p} (f_p^{(2)}(t))^2 dt \} \end{aligned} \quad (5)$$

where $y_1 = (y_{11}, y_{12}, \dots, y_{1n_1})', y_2 = (y_{21}, y_{22}, \dots, y_{2n_2})', \dots, y_p = (y_{p1}, y_{p2}, \dots, y_{pn_p})'$; $f_1 = (f_{11}, f_{12}, \dots, f_{1n_1})', f_2 = (f_{21}, f_{22}, \dots, f_{2n_2})', \dots, f_p = (f_{p1}, f_{p2}, \dots, f_{pn_p})'$, and W_k represents the k^{th} -weight, $k=1,2,\dots,p$ which is obtained from Theorem 1, and the smoothing parameter $\lambda_k (k=1,2,\dots,p)$ controls the trade-off between the goodness of fit and the smoothness of the estimate. The model given in (1) can be expressed into a general smoothing spline regression model as follows:

$$y_{ki} = L_{ki} f_k + \varepsilon_{ki}, k=1,2,\dots,p; i=1,2,\dots,n_k$$

where function $f_k \in F_k$ (F_k represents Hilbert space) is unknown and assumed to be smooth, and $L_{ki} \in F_k$ is a bounded linear functional.

Next, suppose that Hilbert space F_k can be decomposed into direct sum of two subspaces G_k and H_k as follows:

$$F_k = G_k \oplus H_k$$

where $G_k \perp H_k$. Also, suppose that $\{\zeta_{k1}, \zeta_{k2}, \dots, \zeta_{kn_k}\}$ and $\{\vartheta_{k1}, \vartheta_{k2}, \dots, \vartheta_{kn_k}\}$ are bases of spaces of G_k and H_k , respectively. Then, we can express every function $f_k \in F_k (k=1,2,\dots,p)$ into the following expression:

$$f_k = g_k + h_k$$

where $g_k \in G_k$ and $h_k \in H_k$. Since $\{\zeta_{k1}, \zeta_{k2}, \dots, \zeta_{kn_k}\}$ is basis of space G_k , and $\{\vartheta_{k1}, \vartheta_{k2}, \dots, \vartheta_{kn_k}\}$ is basis of space H_k , then for every function $f_k \in F_k (k=1,2,\dots,p)$ follows:

$$f_k = \sum_{v=1}^{m_k} c_{kv} \varepsilon_{kv} + \sum_{i=1}^{n_k} d_{ki} \vartheta_{ki} = \underline{c}'_k b_k + \underline{g}'_k c_k; k = 1, 2, \dots, p; c_{kv}, d_{ki} \in \mathbb{R} \tag{6}$$

where $\underline{c}'_k = (c_{k1}, c_{k2}, \dots, c_{km_k})'$, $c_k = (c_{k1}, c_{k2}, \dots, c_{km_k})'$, $\underline{g}'_k = (g_{k1}, g_{k2}, \dots, g_{kn_k})'$, and $\underline{d}'_k = (d_{k1}, d_{k2}, \dots, d_{kn_k})'$. Finally, since $L_{t_{ki}}$ is the bounded linear function in \mathbf{F}_k , and $f_k \in \mathbf{F}_k$, then we have:

$$L_{t_{ki}} f_k = L_{t_{ki}} (g_k + h_k) = L_{t_{ki}} (g_k) + L_{t_{ki}} (h_k) = g_k(t_{ki}) + h_k(t_{ki}) = f_k(t_{ki}).$$

In the following theorem, we give a method to obtain the estimated regression function by using RKHS method, i.e., by carrying out the PWLS given in (5).

Theorem 2. If the data set $(y_{ki}, t_{ki}), k = 1, 2, \dots, p; i = 1, 2, \dots, n_k$ follows the multiresponse nonparametric regression model given in (1):

$$y_{ki} = f_k(t_{ki}) + \varepsilon_{ki}$$

then the estimated regression function of model (1) based on smoothing spline estimator is given by:

$$\hat{f}_z = A\hat{c} + B\hat{d} = H(\lambda)y$$

where $H(\lambda) = A[A'D^{-1}W(\sigma^2)A]^{-1}A'D^{-1}W(\sigma^2) + BD^{-1}W(\sigma^2) \times [I - A(A'D^{-1}W(\sigma^2)A)^{-1}A'D^{-1}W(\sigma^2)]$.

Proof. By considering model given in (1) and applying Riesz representation theorem (Wang, 2011), and because of $L_{t_{ki}}$ is bounded linear functional in \mathbf{F}_k , then there is a representer $\delta_{t_{ki}} \in \mathbf{F}_k$ of $L_{t_{ki}}$ which follows (Wang, 2011):

$$L_{t_{ki}} f_k = \langle \delta_{t_{ki}}, f_k \rangle = f_k(t_{ki}), f_k \in \mathbf{F}_k$$

where $\langle \cdot, \cdot \rangle$ represents an inner product. Based on (6) and by considering the properties of inner product, we have:

$$f_k(t_{ki}) = \langle \delta_{t_{ki}}, \underline{c}'_k c_k + \underline{g}'_k d_k \rangle = \langle \delta_{t_{ki}}, \underline{c}'_k c_k \rangle + \langle \delta_{t_{ki}}, \underline{g}'_k d_k \rangle. \tag{7}$$

Next, based on (7), for $k = 1$ we have:

$$f_1(t_{i1}) = \langle \delta_{t_{i1}}, \underline{c}'_1 c_1 \rangle + \langle \delta_{t_{i1}}, \underline{g}'_1 d_1 \rangle, i = 1, 2, \dots, n_1;$$

So that, for $i = 1, 2, 3, \dots, n_1$ we have:

$$\underline{f}_1(t_1) = (f_1(t_{11}), f_1(t_{12}), \dots, f_1(t_{1n_1}))' = A_1 \underline{c}_1 + B_1 \underline{d}_1$$

where: $\underline{c}_1 = (c_{11}, c_{12}, \dots, c_{1m_1})'$, $\underline{d}_1 = (d_{11}, d_{12}, \dots, d_{1n_1})'$,

$$A_1 = \begin{bmatrix} \langle \delta_{t_{11}}, \varepsilon_{11} \rangle & \langle \delta_{t_{11}}, \varepsilon_{12} \rangle & \dots & \langle \delta_{t_{11}}, \varepsilon_{1m_1} \rangle \\ \langle \delta_{t_{12}}, \varepsilon_{11} \rangle & \langle \delta_{t_{12}}, \varepsilon_{12} \rangle & \dots & \langle \delta_{t_{12}}, \varepsilon_{1m_1} \rangle \\ \vdots & \vdots & \vdots & \vdots \\ \langle \delta_{t_{1n_1}}, \varepsilon_{11} \rangle & \langle \delta_{t_{1n_1}}, \varepsilon_{12} \rangle & \dots & \langle \delta_{t_{1n_1}}, \varepsilon_{1m_1} \rangle \end{bmatrix}, B_1 = \begin{bmatrix} \langle \delta_{t_{11}}, \vartheta_{11} \rangle & \langle \delta_{t_{11}}, \vartheta_{12} \rangle & \dots & \langle \delta_{t_{11}}, \vartheta_{1n_1} \rangle \\ \langle \delta_{t_{12}}, \vartheta_{11} \rangle & \langle \delta_{t_{12}}, \vartheta_{12} \rangle & \dots & \langle \delta_{t_{12}}, \vartheta_{1n_1} \rangle \\ \vdots & \vdots & \vdots & \vdots \\ \langle \delta_{t_{1n_1}}, \vartheta_{11} \rangle & \langle \delta_{t_{1n_1}}, \vartheta_{12} \rangle & \dots & \langle \delta_{t_{1n_1}}, \vartheta_{1n_1} \rangle \end{bmatrix}.$$

In the similar process, we obtain: $\underline{f}_2(t_2) = A_2 \underline{c}_2 + B_2 \underline{d}_2, \dots, \underline{f}_p(t_p) = A_p \underline{c}_p + B_p \underline{d}_p$. Therefore, the regression function $\underline{f}(t)$ can be expressed as:

$$\begin{aligned} \underline{f}(t) &= (f_1(t_1), f_2(t_2), \dots, f_p(t_p))' = (A_1 c_1, A_2 c_2, \dots, A_p c_p)' + (B_1 d_1, B_2 d_2, \dots, B_p d_p)' \\ &= \text{diag}(A_1, A_2, \dots, A_p)(c_1, c_2, \dots, c_p)' + \text{diag}(B_1, B_2, \dots, B_p)(d_1, d_2, \dots, d_p)' = A \underline{c} + B \underline{d}. \end{aligned} \tag{8}$$

In equation (8), A is a $(N \times M)$ -matrix, where $N = \sum_{k=1}^p n_k$, $M = \sum_{k=1}^p m_k$, and \underline{c} is a $(M \times 1)$ -vector of parameters that are expressed as $A = \text{diag}(A_1, A_2, \dots, A_p)$, and $\underline{c} = (c_1', c_2', \dots, c_p')'$, respectively. Also, B is $(N \times N)$ -matrix, and \underline{d} is a $(N \times 1)$ -vector of parameters which are expressed as $B = \text{diag}(B_1, B_2, \dots, B_p)$, and $\underline{d} = (d_1', d_2', \dots, d_p')'$, respectively. Therefore, we can write the multiresponse nonparametric regression model given in (1) or (3) as $\underline{y} = A \underline{c} + B \underline{d} + \underline{\varepsilon}$. To obtain the estimation of regression function, \underline{f} , we use RKHS method by solving the following optimization:

$$\text{Min}_{\substack{f_k \in W_2^m[a_k, b_k] \\ k=1,2,\dots,p}} \left\{ \left\| W^{\frac{1}{2}}(\sigma^2) \underline{\varepsilon} \right\|^2 \right\} = \text{Min}_{\substack{f_k \in W_2^m[a_k, b_k] \\ k=1,2,\dots,p}} \left\{ \left\| W^{\frac{1}{2}}(\sigma^2)(\underline{y} - \underline{f}) \right\|^2 \right\}, \tag{9}$$

with constraint $\int_{a_k}^{b_k} [f_k^{(m)}(t_k)]^2 dt_k < \gamma_k$, $\gamma_k \geq 0$. The solution to (9) is equivalent to solution to the penalized weighted least-square (PWLS):

$$\text{Min}_{\substack{f_k \in W_2^m[a_k, b_k] \\ k=1,2,\dots,p}} \left\{ N^{-1}(\underline{y} - \underline{f})' W(\sigma^2)(\underline{y} - \underline{f}) + \sum_{k=1}^p \lambda_k \int_{a_k}^{b_k} [f_k^{(m)}(t_k)]^2 dt_k \right\}, \tag{10}$$

where λ_k , $k = 1, 2, \dots, p$ are smoothing parameters that control between goodness of fit represented by $N^{-1}(\underline{y} - \underline{f})' W(\sigma^2)(\underline{y} - \underline{f})$ and smoothness of the estimate measured by $\lambda_1 \int_{a_1}^{b_1} [f_1^{(m)}(t_1)]^2 dt_1 + \dots + \lambda_p \int_{a_p}^{b_p} [f_p^{(m)}(t_p)]^2 dt_p$. To determine the solution to (10), we first decompose the penalty as follows:

$$\int_{a_1}^{b_1} [f_1^{(m)}(t_1)]^2 dt_1 = \|P f_1\|^2 = \langle P f_1, P f_1 \rangle = \langle \mathcal{G}' d_1, \mathcal{G}' d_1 \rangle = d_1' (\mathcal{G}' \mathcal{G}) d_1 = d_1' B_1 d_1.$$

Therefore, the penalty in (10) is $\sum_{k=1}^p \lambda_k \int_{a_k}^{b_k} [f_k^{(m)}(t_k)]^2 dt_k = \underline{d}' \lambda B \underline{d}$ where $\lambda = \text{diag}(\lambda_1 I_{n_1}, \dots, \lambda_p I_{n_p})$. So, the goodness of fit in (10) can be written as:

$$N^{-1}(\underline{y} - \underline{f})' W(\sigma^2)(\underline{y} - \underline{f}) = N^{-1}(\underline{y} - A \underline{c} - B \underline{d})' W(\sigma^2)(\underline{y} - A \underline{c} - B \underline{d}).$$

By combining the goodness of fit and penalty, we obtain optimization PWLS:

$$\text{Min}_{\substack{c \in R^m \\ d \in R^m}} \{ Q(c, d) \} = \text{Min}_{\substack{f_k \in W_2^m[a_k, b_k] \\ k=1,2,\dots,p}} \left\{ N^{-1}(\underline{y} - \underline{f})' W(\sigma^2)(\underline{y} - \underline{f}) + \sum_{k=1}^p \lambda_k \int_{a_k}^{b_k} [f_k^{(m)}(t_k)]^2 dt_k \right\}. \tag{11}$$

Optimization PWLS in (11) gives $\hat{c} = [A'D^{-1}W(\sigma^2)A]^{-1} A'D^{-1}W(\sigma^2)\underline{y}$ and $\hat{d} = D^{-1}W(\sigma^2)[I - A(A'D^{-1}W(\sigma^2)A)^{-1} A'D^{-1}W(\sigma^2)]\underline{y}$, where $D = W(\sigma^2)B + N\lambda I$. Finally, we get the estimated regression function of model given in (1):

$$\hat{f}_{\lambda} = (\hat{f}_{1,\lambda_1}, \hat{f}_{2,\lambda_2}, \dots, \hat{f}_{p,\lambda_p})' = A \hat{c} + B \hat{d} = H(\lambda) \underline{y} \tag{12}$$

where $H(\lambda) = A[A'D^{-1}W(\sigma^2)A]^{-1} A'D^{-1}W(\sigma^2) + B D^{-1}W(\sigma^2) \times [I - A(A'D^{-1}W(\sigma^2)A)^{-1} A'D^{-1}W(\sigma^2)]$.

3.3 Estimation of covariance matrix of random errors

Suppose that $[W(\sigma^2)]^{-1}$ represents an estimated covariance matrix of random errors. To obtain the estimated covariance matrix, we consider the data set $(t_{ki}, y_{ki}), k = 1, 2, \dots, p; i = 1, 2, \dots, n_k$ follows the model in (3). Assume that $\underline{y} = (y_1, y_2, \dots, y_p)'$ is random sample obtained from N-variate normally distributed population $(N = \sum_{k=1}^p n_k)$ with mean \underline{f} , and covariance $[W(\sigma^2)]^{-1}$. Based on this distribution, we get likelihood function as follows:

$$L(\underline{f}, W(\sigma^2) | \underline{y}) = \prod_{j=1}^n \left\{ \frac{1}{(2\pi)^{\frac{n}{2}} |W(\sigma^2)|^{\frac{1}{2}}} \exp\left\{-\frac{1}{2}(\underline{y}_j - \underline{f}_j)' [W(\sigma^2)]^{-1} (\underline{y}_j - \underline{f}_j)\right\}\right\}$$

Since $N = \sum_{k=1}^p n_k$ and $W(\sigma^2) = \text{diag}(W_1(\sigma_1^2), W_2(\sigma_2^2), \dots, W_p(\sigma_p^2))$ then we have:

$$L(\underline{f}, W(\sigma^2) | \underline{y}) = \left\{ \frac{1}{(2\pi)^{\frac{n}{2}} |W_1(\sigma_1^2)|^{\frac{1}{2}}} \exp\left\{-\frac{1}{2} \sum_{j=1}^n (y_{1j} - f_{1j})' W_1(\sigma_1^2) (y_{1j} - f_{1j})\right\}\right\} \times$$

$$\left\{ \frac{1}{(2\pi)^{\frac{n_2}{2}} |W_2(\sigma_2^2)|^{\frac{1}{2}}} \exp\left\{-\frac{1}{2} \sum_{j=1}^n (y_{2j} - f_{2j})' W_2(\sigma_2^2) (y_{2j} - f_{2j})\right\}\right\} \times \dots \times$$

$$\left\{ \frac{1}{(2\pi)^{\frac{n_p}{2}} |W_p(\sigma_p^2)|^{\frac{1}{2}}} \exp\left\{-\frac{1}{2} \sum_{j=1}^n (y_{pj} - f_{pj})' W_p(\sigma_p^2) (y_{pj} - f_{pj})\right\}\right\}.$$

Next, estimated covariance matrix of random error can be obtained by carrying out the following optimization:

$$L(\underline{f}, W(\sigma^2) | \underline{y}) = \left[\text{Max}_{W_1(\sigma_1^2)} \left\{ \frac{1}{(2\pi)^{\frac{n}{2}} |W_1(\sigma_1^2)|^{\frac{1}{2}}} \exp\left\{-\frac{1}{2} \sum_{j=1}^n (y_{1j} - f_{1j})' W_1(\sigma_1^2) (y_{1j} - f_{1j})\right\}\right\} \right] \times$$

$$\left[\text{Max}_{W_2(\sigma_2^2)} \left\{ \frac{1}{(2\pi)^{\frac{n_2}{2}} |W_2(\sigma_2^2)|^{\frac{1}{2}}} \exp\left\{-\frac{1}{2} \sum_{j=1}^n (y_{2j} - f_{2j})' W_2(\sigma_2^2) (y_{2j} - f_{2j})\right\}\right\} \right] \times \dots \times$$

$$\left[\text{Max}_{W_p(\sigma_p^2)} \left\{ \frac{1}{(2\pi)^{\frac{n_p}{2}} |W_p(\sigma_p^2)|^{\frac{1}{2}}} \exp\left\{-\frac{1}{2} \sum_{j=1}^n (y_{pj} - f_{pj})' W_p(\sigma_p^2) (y_{pj} - f_{pj})\right\}\right\} \right]. \tag{13}$$

Determining of value $L(\underline{f}, W(\sigma^2) | \underline{y})$ in (13) is equivalent to determining of maximum value of each component in (13) (Johnson & Wichern, 1982). It means that the maximum value of each component in (13) can be determined by giving the following equations:

$$[W_1(\hat{\sigma}_1^2)] = \frac{\hat{\underline{e}}_1 \hat{\underline{e}}_1'}{n} = \frac{(y_1 - \hat{f}_{1,\mathcal{A}_1})(y_1 - \hat{f}_{1,\mathcal{A}_1})'}{n}, \dots,$$

$$[W_p(\hat{\sigma}_p^2)] = \frac{\hat{\xi}_p \hat{\xi}_p'}{n} = \frac{(y_p - \hat{f}_{p,\lambda_p})(y_p - \hat{f}_{p,\lambda_p})'}{n}$$

where $\hat{f}_{k,\lambda}$ ($k=1,2,\dots,p$) is regression function estimator given in (12). Therefore, the maximum likelihood estimator for $[W(\hat{\sigma}^2)]$ is given by:

$$\begin{aligned} [W(\hat{\sigma}^2)] &= \text{diag}([W_1(\hat{\sigma}_1^2)], [W_2(\hat{\sigma}_2^2)], \dots, [W_p(\hat{\sigma}_p^2)]) \\ &= \text{diag}\left(\frac{(y_1 - \hat{f}_{1,\lambda_1})(y_1 - \hat{f}_{1,\lambda_1})'}{n}, \frac{(y_2 - \hat{f}_{2,\lambda_2})(y_2 - \hat{f}_{2,\lambda_2})'}{n}, \dots, \frac{(y_p - \hat{f}_{p,\lambda_p})(y_p - \hat{f}_{p,\lambda_p})'}{n}\right) \end{aligned}$$

Since $\hat{f}_{k,\lambda_k} = H(\lambda_k; \hat{\sigma}_k^2) y_k$, $k=1,2,\dots,p$ then for $k=1,2,\dots,p$ we have:

$$\begin{aligned} \frac{(y_1 - \hat{f}_{1,\lambda_1})(y_1 - \hat{f}_{1,\lambda_1})'}{n} &= \frac{(I_{n_1} - H(\lambda_1; \hat{\sigma}_1^2)) y_1 y_1' (I_{n_1} - H(\lambda_1; \hat{\sigma}_1^2))'}{n}, \dots, \\ \frac{(y_p - \hat{f}_{p,\lambda_p})(y_p - \hat{f}_{p,\lambda_p})'}{n} &= \frac{(I_{n_p} - H(\lambda_p; \hat{\sigma}_p^2)) y_p y_p' (I_{n_p} - H(\lambda_p; \hat{\sigma}_p^2))'}{n}. \end{aligned}$$

Therefore, the maximum likelihood estimator for covariance matrix is given by:

$$\begin{aligned} [W(\hat{\sigma}^2)]^{-1} &= \text{diag}\left(\left[\frac{(y_1 - \hat{f}_{1,\lambda_1})(y_1 - \hat{f}_{1,\lambda_1})'}{n}\right]^{-1}, \dots, \left[\frac{(y_p - \hat{f}_{p,\lambda_p})(y_p - \hat{f}_{p,\lambda_p})'}{n}\right]^{-1}\right) \\ &= \text{diag}([W_1(\hat{\sigma}_1^2)]^{-1}, [W_2(\hat{\sigma}_2^2)]^{-1}, \dots, [W_p(\hat{\sigma}_p^2)]^{-1}). \end{aligned}$$

where:

$$[W_1(\hat{\sigma}_1^2)] = \frac{[I_{n_1} - H(\lambda_1; \hat{\sigma}_1^2)] y_1 y_1' [I_{n_1} - H(\lambda_1; \hat{\sigma}_1^2)]'}{n}, \dots, [W_p(\hat{\sigma}_p^2)] = \frac{[I_{n_p} - H(\lambda_p; \hat{\sigma}_p^2)] y_p y_p' [I_{n_p} - H(\lambda_p; \hat{\sigma}_p^2)]'}{n}.$$

3.4 Estimation of optimum smoothing parameter

Selecting an optimum (suitable) smoothing parameter value λ is crucial to good regression function fitting. There are a number of ways to choose λ , including minimizing Mallows's C_p , cross-validation (CV) score, generalized cross-validation (GCV) score, and Akaike's information criterion (AIC) (Li & Zhang, 2010). Ruppert and Carroll (1997) pointed out that Mallows's C_p and GCV were satisfactory for good regression function fitting based on spline estimator. Moreover, GCV approximating CV is a computationally expedient criterion, so it is popular in spline literature.

In this section we establish the estimation of optimum smoothing parameter to good function regression fitting. For this goal, we may express the estimated regression function given in (12) as follows:

$$\hat{f}_\lambda(t) = H(\lambda_1, \lambda_2, \dots, \lambda_p; \sigma^2) y \quad (14)$$

where $\sigma^2 = (\sigma_1^2, \sigma_2^2, \dots, \sigma_p^2)'$. The mean square error (MSE) of the smoothing spline estimator given in (14) is:

$$MSE(\lambda_1, \lambda_2, \dots, \lambda_p; \sigma^2) = \frac{(y - \hat{f}_\lambda(t))' W(\sigma^2) (y - \hat{f}_\lambda(t))}{\sum_{k=1}^p n_k}$$

$$= \frac{[(I - H(\lambda_1, \lambda_2, \dots, \lambda_p; \sigma^2))y]'W(\sigma^2)[(I - H(\lambda_1, \lambda_2, \dots, \lambda_p; \sigma^2))y]}{\sum_{k=1}^p n_k}$$

$$= \frac{\left\| [W(\sigma^2)]^{\frac{1}{2}} [(I - H(\lambda_1, \lambda_2, \dots, \lambda_p; \sigma^2))y] \right\|^2}{\sum_{k=1}^p n_k}$$

Next, we define the following quantity:

$$G(\lambda_1, \lambda_2, \dots, \lambda_p; \sigma^2) = \frac{\left(\sum_{k=1}^p n_k \right)^{-1} \left\| [W(\sigma^2)]^{\frac{1}{2}} [(I - H(\lambda_1, \lambda_2, \dots, \lambda_p; \sigma^2))y] \right\|^2}{\left[\left(\frac{1}{\sum_{k=1}^p n_k} \right) \text{trace} \left(I_{\sum_{k=1}^p n_k} - H(\lambda_1, \lambda_2, \dots, \lambda_p; \sigma^2) \right) \right]^2} \quad (15)$$

Therefore, based on (15), the optimum smoothing parameter, $\hat{\lambda}_{opt} = (\hat{\lambda}_{1(opt)}, \hat{\lambda}_{2(opt)}, \dots, \hat{\lambda}_{p(opt)})'$, is obtained by solving the following optimization:

$$G_{opt}(\hat{\lambda}_{1(opt)}, \hat{\lambda}_{2(opt)}, \dots, \hat{\lambda}_{p(opt)}; \sigma^2) = \underset{\lambda_1 \in \mathbb{R}^+, \lambda_2 \in \mathbb{R}^+, \dots, \lambda_p \in \mathbb{R}^+}{\text{Min}} \{G(\lambda_1, \lambda_2, \dots, \lambda_p; \sigma^2)\}$$

$$= \underset{\lambda_1 \in \mathbb{R}^+, \lambda_2 \in \mathbb{R}^+, \dots, \lambda_p \in \mathbb{R}^+}{\text{Min}} \left\{ \frac{\left(\sum_{k=1}^p n_k \right)^{-1} \left\| [W(\sigma^2)]^{\frac{1}{2}} [(I - H(\lambda_1, \lambda_2, \dots, \lambda_p; \sigma^2))y] \right\|^2}{\left[\left(\frac{1}{\sum_{k=1}^p n_k} \right) \text{trace} \left(I_{\sum_{k=1}^p n_k} - H(\lambda_1, \lambda_2, \dots, \lambda_p; \sigma^2) \right) \right]^2} \right\}$$

where norm $\|y\| = \sqrt{v_1^2 + v_2^2 + \dots + v_p^2}$ for a p -dimension vector $y = (v_1, v_2, \dots, v_p)'$.

3.5 Asymptotic properties of spline estimator

In this section, we investigate the asymptotic properties of spline estimator \hat{f}_{λ} of the multiresponse nonparametric regression model. Our goal is to investigate asymptotic properties of spline estimator \hat{f}_{λ} and we will judge the quantity of spline estimator \hat{f}_{λ} by weighted integrated mean square error (IMSE).

Firstly, we decompose $IMSE(\hat{\lambda})$ into two components as follows:

$$IMSE(\hat{\lambda}) = E \int_a^b [(f(t) - \hat{f}_{\lambda}(t))'W(\sigma^2)(f(t) - \hat{f}_{\lambda}(t))] dt = bias^2(\hat{\lambda}) + Var(\hat{\lambda})$$

where $bias^2 = \int_a^b E[(f(t) - E(\hat{f}_{\lambda}(t)))'W(\sigma^2)(f(t) - E(\hat{f}_{\lambda}(t)))] dt$, and $Var(\hat{\lambda}) = \int_a^b E[(E\hat{f}_{\lambda}(t) - \hat{f}_{\lambda}(t))'W(\sigma^2)(E\hat{f}_{\lambda}(t) - \hat{f}_{\lambda}(t))] dt$.

Next, to investigate the asymptotic property of $bias^2(\hat{\lambda})$, we first establish the solution of PWLS optimization in the following Theorem.

Theorem 3. If $\hat{f}_\lambda(t)$ is solution which minimize the following PWLS:

$$\left(\sum_{k=1}^p n_k\right)^{-1} (y - g(t))' W(\sigma^2) (y - g(t)) + \sum_{k=1}^p \lambda_k \int_a^b (g_k^{(m)}(t_k))^2 dt_k$$

then the solution which minimize the following PWLS:

$$\left(\sum_{k=1}^p n_k\right)^{-1} (f(t) - g(t))' W(\sigma^2) (f(t) - g(t)) + \sum_{k=1}^p \lambda_k \int_a^b (g_k^{(m)}(t_k))^2 dt_k \text{ is } \hat{g}_\lambda^*(t) = E\hat{f}_\lambda(t).$$

Proof. Theorem 2 has given the solution which minimize the following PWLS:

$$\left(\sum_{k=1}^p n_k\right)^{-1} (y - g(t))' W(\sigma^2) (y - g(t)) + \sum_{k=1}^p \lambda_k \int_a^b (g_k^{(m)}(t_k))^2 dt_k.$$

The solution is:

$$\hat{f}_\lambda(t) = \{A[A'D^{-1}W(\sigma^2)A]^{-1}A'D^{-1}W(\sigma^2) + BD^{-1}W(\sigma^2)[I - A(A'D^{-1}W(\sigma^2)A)^{-1}A'D^{-1}W(\sigma^2)]\}y$$

Next, by taking $f(t) = y$, then the value that minimize:

$$\left(\sum_{k=1}^p n_k\right)^{-1} (f(t) - g(t))' W(\sigma^2) (f(t) - g(t)) + \sum_{k=1}^p \lambda_k \int_a^b (g_k^{(m)}(t_k))^2 dt_k \text{ can be written as:}$$

$$\hat{g}_\lambda^*(t) = \{A[A'D^{-1}W(\sigma^2)A]^{-1}A'D^{-1}W(\sigma^2) + BD^{-1}W(\sigma^2)[I - A(A'D^{-1}W(\sigma^2)A)^{-1}A'D^{-1}W(\sigma^2)]\}f(t) = E\hat{f}_\lambda(t).$$

Furthermore, we investigate the asymptotic property of $bias^2(\lambda)$. For this goal, we first give the following assumption.

Assumption. (A0). For every k ($k = 1, 2, \dots, p$), $t_{ki} = \frac{2i-1}{2n}$, $i = 1, 2, \dots, n$.

The asymptotic property of $bias^2(\lambda)$ can be established in Theorem 4 under assumption (A0).

Theorem 4. If assumption (A0) hold, then $bias^2(\lambda) \leq O(\lambda)$ as $n \rightarrow \infty$ where $O(\lambda)$ represents "big oh" (Sen & Singer, 1993, and Wand & Jones, 1995).

Proof. Suppose $\hat{g}_\lambda(t)$ is value which minimize:

$$\int_a^b (f(t) - g(t))' W(\sigma^2) (f(t) - g(t)) dt + \sum_{k=1}^p \lambda_k \int_a^b [g_k^{(m)}(t_k)]^2 dt_k.$$

Since assumption (A0) then, as $n \rightarrow \infty$,

$$\left(\sum_{k=1}^p n_k\right)^{-1} (f(t) - g(t))' W(\sigma^2) (f(t) - g(t)) \approx \int_a^b (f(t) - g(t))' W(\sigma^2) (f(t) - g(t)) dt$$

It implies $\hat{g}_\lambda^*(t) = E\hat{f}_\lambda(t) \approx \hat{g}_\lambda(t)$

(16)

So, for every $g \in W_2^m[a, b]$, we have $bias^2(\lambda) = \int_a^b E(f(t) - \hat{f}_\lambda(t))' W(\sigma^2) (f(t) - \hat{f}_\lambda(t)) dt$

$$\leq \int_a^b E(\underline{f}(t) - \hat{E}\underline{f}_\lambda(t))' W(\sigma^2)(\underline{f}(t) - \hat{E}\underline{f}_\lambda(t)) dt + \sum_{k=1}^p \lambda_k \int_a^b \hat{g}_{k\lambda}^{(m)}(t_k) dt_k$$

By considering $\hat{E}\underline{f}_\lambda(t) \approx \hat{g}_\lambda(t)$ as given in (16), we obtain:

$$bias^2(\lambda) \leq \int_a^b E(\underline{f}(t) - \hat{g}_\lambda(t))' W(\sigma^2)(\underline{f}(t) - \hat{g}_\lambda(t)) dt + \sum_{k=1}^p \lambda_k \int_a^b \hat{g}_{k\lambda}^{(m)}(t_k) dt_k$$

Thus, for every $\underline{g} \in W_2^m[a, b]$, we have the following relationship:

$$bias^2(\lambda) \leq \int_a^b E(\underline{f}(t) - \underline{g}(t))' W(\sigma^2)(\underline{f}(t) - \underline{g}(t)) dt + \sum_{k=1}^p \lambda_k \int_a^b g_k^{(m)}(t_k) dt_k \tag{17}$$

Since (17) hold for every $\underline{g} \in W_2^m[a, b]$, then by taking $\underline{g}(t) = \underline{f}(t)$ we get:

$$bias^2(\lambda) \leq \sum_{k=1}^p \lambda_k \int_a^b [g_k^{(m)}(t_k)]^2 dt_k = O(\lambda), \text{ as } n \rightarrow \infty.$$

Next, to determine the asymptotic property of $Var(\lambda)$ we first define:

$$\Phi(\hat{\underline{f}}_\lambda, h, \gamma) = R(\hat{\underline{f}}_\lambda + \gamma h) + \sum_{k=1}^p \lambda_k J_k(\hat{\underline{f}}_\lambda + \gamma h), \quad \gamma \in R, \text{ and } h \in W_2^m[a, b]$$

where $R(\underline{g}) = (\sum_{k=1}^p n_k)^{-1} (\underline{y} - \underline{g}(t))' W(\sigma^2)(\underline{y} - \underline{g}(t))$, and $J_k(\underline{g}) = \int_a^b [g_k^{(m)}(t_k)]^2 dt_k$.

For any $\underline{f}, \underline{g} \in W_2^m[a, b]$, we have

$$\Phi(\underline{f}, \underline{g}, \gamma) = (\sum_{k=1}^p n_k)^{-1} (\underline{y} - \underline{f}(t) - \gamma \underline{g}(t))' W(\sigma^2)(\underline{y} - \underline{f}(t) - \gamma \underline{g}(t)) + \sum_{k=1}^p \lambda_k \int_a^b (f_k^{(m)}(t_k) + \gamma g_k^{(m)}(t_k))^2 dt_k$$

By carrying out $d\Phi(\underline{f}, \underline{g}, \gamma)/d\gamma = 0$ and $\gamma = 0$, it will give:

$$(\sum_{k=1}^p n_k)^{-1} (\underline{y} - \underline{f}(t))' W(\sigma^2) \underline{g}(t) = \sum_{k=1}^p \lambda_k \int_a^b f_k^{(m)}(t_k) g_k^{(m)}(t_k) dt_k$$

Suppose $\varphi_1, \varphi_2, \dots, \varphi_n$ are basis of natural splines and $f(t) = \sum_{j=1}^n \beta_j \varphi_j(t)$, then according to Eubank (1988), it will give:

$$\sum_{i=0}^n W_i(\sigma^2) g(t_i) (y_i - \sum_{j=1}^n \beta_j \varphi_j(t_i)) = n\lambda(-1)^m(2m-1)! \sum_{i=1}^n g(t_i) \sum_{j=1}^n \beta_j d_{ij} \tag{18}$$

Since (18) is hold for every $\underline{g} \in W_2^m[a, b]$, then equation (23) is equivalent to determine β_j which holds:

$$y_i = \sum_{j=1}^n (n\lambda(-1)^m(2m-1)! W_i^{-1}(\sigma^2) d_{ij} + \varphi_j(t_i)) \beta_j, \quad i = 1, 2, \dots, n \tag{19}$$

We can express (19) in the following matrix notation:

$$y = (n\lambda(-1)^m (2m-1)! W^{-1}(\sigma^2) K + \varphi) \beta$$

where $K = \{d_{ij}\}$, $i, j = 1, 2, \dots, n$, and $\varphi = \{\varphi_j(t_i)\}$, $i, j = 1, 2, \dots, n$. So, we obtain:

$$y = (n\lambda W^{-1}(\sigma^2) FB^{-1} F' W^{-1}(\sigma^2) \varphi + \varphi) \beta, \text{ where } B = F' V F. \quad (20)$$

If we multiply equation (20) from the left side with φ' , then we will have:

$$\varphi' y = (n\lambda \varphi' W^{-1}(\sigma^2) FB^{-1} F' W^{-1}(\sigma^2) \varphi + \varphi' \varphi) \beta.$$

So, we get the estimator $\hat{\beta}_\lambda$ of β as follows:

$$\hat{\beta}_\lambda = \text{diag} \left((1 + n\lambda\theta_1)^{-1}, \dots, (1 + n\lambda\theta_n)^{-1} \right) \varphi' y.$$

Thus, we can express the estimator $\hat{f}_\lambda(t)$ as follows:

$$\hat{f}_\lambda(t) = \varphi(t) \hat{\beta}_\lambda = \sum_{j=1}^n \frac{1}{1 + n\lambda\theta_j} \varphi'_j y \varphi_j(t) \quad (21)$$

The asymptotic properties of $\text{Var}(\hat{\lambda}_k)$ can be established in Theorem 5 under assumption (A0).

Theorem 5. If assumption (A0) hold, then for $k = 1, 2, \dots, p$, $\text{Var}(\hat{\lambda}_k) \leq O\left(\frac{1}{n\lambda_k^{\frac{2m}{m}}}\right)$, as $n \rightarrow \infty$.

Proof. For $k = 1, 2, \dots, p$, the equation (21) gives:

$$\hat{f}_{\lambda_k}(t) = \sum_{j=1}^n \frac{1}{1 + n\lambda_k \theta_j} \varphi'_j y \varphi_j(t)$$

It implies: $\text{Var}(\hat{f}_{\lambda_k}(t)) \leq \left(\text{Max}\{W_i^{-1}(\sigma^2)\}_{1 \leq i \leq n} \right) \sigma^2 \sum_{j=1}^n \frac{\varphi_j^2(t)}{(1 + n\lambda_k \theta_j)^2}$

So, we have: $\text{Var}(\hat{\lambda}_k) \leq \left(\text{Max}\{W_i^{-1}(\sigma^2)\}_{1 \leq i \leq n} \right) \sigma^2 \sum_{j=1}^n \frac{\varphi_j^2(t)}{(1 + n\lambda_k \theta_j)^2} \int_a^b \varphi_j^2(t) W(\sigma^2) dt$.

Speckman (1985), and Eubank(1988) have given the following approximation:

$$n^{-1} = n^{-1} \sum_{j=1}^n W_j(\sigma^2) \varphi_j^2(t_j) \approx \int_a^b \varphi_k^2(t) W(\sigma^2) dt \text{ and } \text{Var}(\hat{\lambda}_k) \leq \left(\text{Max}\{W_i^{-1}(\sigma^2)\}_{1 \leq i \leq n} \right) \sigma^2 n^{-1} \sum_{j=1}^n \frac{1}{(1 + \lambda_k \gamma_j)^2} \text{ as } n \rightarrow \infty.$$

Furthermore, Eubank (1988) has given:

$$\text{Var}(\hat{\lambda}_k) \leq \left(\text{Max}\{W_i^{-1}(\sigma^2)\}_{1 \leq i \leq n} \right) \sigma^2 n^{-1} \sum_{j=1}^n \frac{1}{[(1 + \lambda_k (\pi j)^{2m})]^2}$$

By integral approximation, we obtain:

$$\text{Var}(\lambda_k) \leq \left(\text{Max}_{1 \leq i \leq n} \{W_i^{-1}(\sigma^2)\} \right) \frac{\sigma^2}{\pi n \lambda_k^{2m}} \int_a^b \frac{dt}{(1+t^{2m})^2} = \frac{1}{n \lambda_k^{2m}} K(m, \sigma) = O\left(\frac{1}{n \lambda_k^{2m}}\right)$$

where $K(m, \sigma) = \frac{\sigma^2}{\pi} \left(\text{Max}_{1 \leq i \leq n} \{W_i^{-1}(\sigma^2)\} \right) \int_a^b \frac{dt}{(1+t^{2m})^2}$.

Finally, based on Theorem 4 and Theorem 5, we obtain the asymptotic property of spline estimator based on IMSE criterion as follows:

$$\text{IMSE}(\hat{\lambda}) = \text{bias}^2(\hat{\lambda}) + \text{Var}(\hat{\lambda}) \leq O(\hat{\lambda}) + O(s) \tag{22}$$

where $s = \left(\frac{1}{n \lambda_1^{2m}}, \frac{1}{n \lambda_2^{2m}}, \dots, \frac{1}{n \lambda_p^{2m}} \right)'$.

3.6 Numerical example

In this section we give a numerical example of estimation of the multiresponse nonparametric regression model based on smoothing spline method where performance of this method depends on the selection of smoothing parameters. For this example, we generate data for $n=100$, correlations $\rho_{12}=0.6$, $\rho_{13}=0.7$, $\rho_{23}=0.8$, and variances $\sigma_1^2=2$, $\sigma_2^2=3$, $\sigma_3^2=4$. The underlying multiresponse nonparametric regression model is:

$$\left. \begin{aligned} y_{1i} &= 5 + 3 \sin(2\pi t_{1i}^2) + \varepsilon_{1i}, & i=1,2,\dots,n \\ y_{2i} &= 3 + 3 \sin(2\pi t_{2i}^2) + \varepsilon_{2i}, & i=1,2,\dots,n \\ y_{3i} &= 1 + 3 \sin(2\pi t_{3i}^2) + \varepsilon_{3i}, & i=1,2,\dots,n \end{aligned} \right\} \tag{23}$$

In this example, we conduct simulation to compare three different smoothing parameters (λ), i.e., $\lambda=1e-09$ (small lambda), $\lambda=2.27e-07$ (optimum lambda), and $\lambda=1e-05$ (great lambda). A plot of GCV versus lambda (λ) that gives minimum GCV value at lambda, $\lambda_{\text{optimum}}=2.27e-07$ is given in Figure 1.

Next, a plot of the estimated regression function of the model in (23) for optimum lambda, $\lambda_{\text{optimum}}=2.27e-07$, is given in Figure 2. A plot of the estimated regression function of the model in (23) for small lambda, $\lambda=1e-09$, is given in Figure 3. Also, a plot of the estimated regression function of the model in (23) for great lambda, $\lambda=1e-05$, is given in Figure 4. Figures 2, 3, and 4 show that selection smoothing parameters, i.e., optimum lambda ($\lambda_{\text{optimum}}=2.27e-07$), small lambda ($\lambda=1e-09$), and great lambda ($\lambda=1e-05$) give a good regression function fitting, a too rough regression function fitting, and a too smooth regression function fitting, respectively.

In the following Table 1, we give the comparison of three different smoothing parameters (λ) in estimating the regression function of the multiresponse nonparametric regression model.

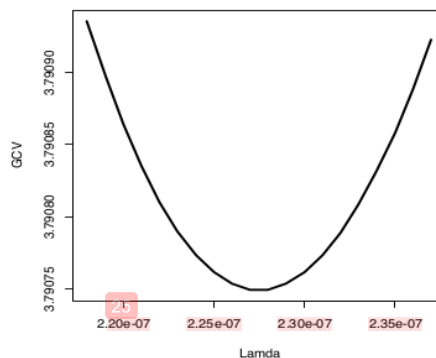


Figure 1. Plot of GCV versus lambda (λ) that gives minimum GCV value at lambda, $\lambda_{\text{optimum}}=2.27e-07$.

Table 1 shows that the optimum smoothing parameter ($\lambda_{\text{optimum}}=2.27e-07$) gives the most minimum GCV value compared with both small smoothing parameter ($\lambda=1e-09$) and great smoothing parameter ($\lambda=1e-05$). It means that the selection of optimum smoothing parameter gives the best regression function fitting of the multiresponse nonparametric regression model.

Table 1. Results of estimation for three different smoothing parameters.

Smoothing parameters	Minimum GCV values	Results of estimation
$\lambda=1e-09$ (small lambda)	5.687333	A too rough regression function fitting.
$\lambda=2.27e-07$ (optimum lambda)	3.79075	A good regression function fitting.
$\lambda=1e-05$ (great lambda)	5.470145	A too smooth regression function fitting.

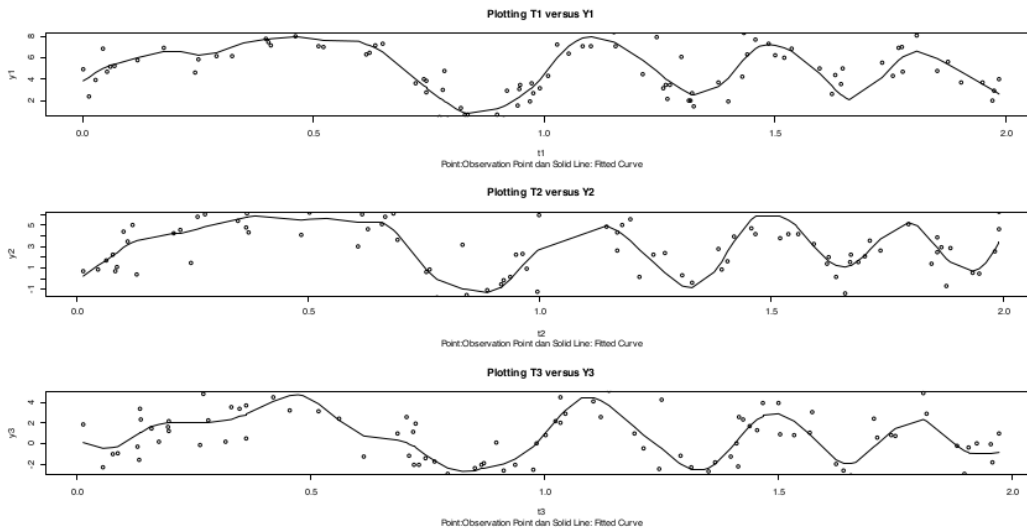


Figure 2. Plots of estimation of the first response (above), the second response (central), and the third response (below) of model (23) for optimum lambda, $\lambda_{optimum} = 2.27e - 07$.

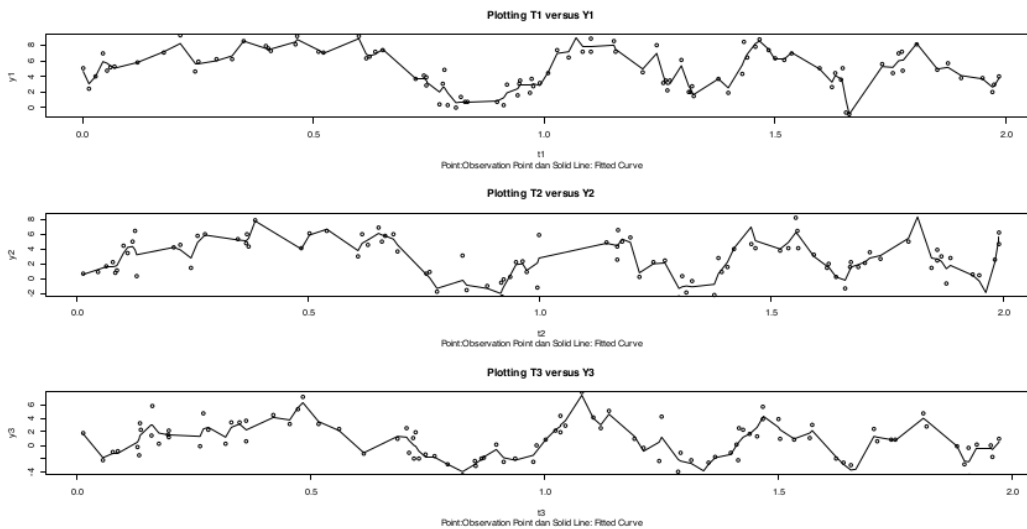


Figure 3. Plots of estimation of the first response (above), the second response (central), and the third response (below) of model (23) for small lambda, $\lambda = 1e - 09$.

4. Conclusion

By assuming that the distribution of response variable is known, we can get the estimation of covariance matrix by using maximum likelihood method. The optimum smoothing parameter (λ) is obtained by minimizing the generalized cross validation (GCV). Optimum lambda (λ) gives a good regression function fitting. In estimating of the

regression function of the multiresponse nonparametric regression model based on smoothing spline estimator, we use all observation points as knots. Smoothing spline estimate of the functions f_j arises as a solution to the minimization problem, i.e., find \hat{f}_j that minimizes the penalized weighted least-square (PWLS). The result shows that smoothing spline

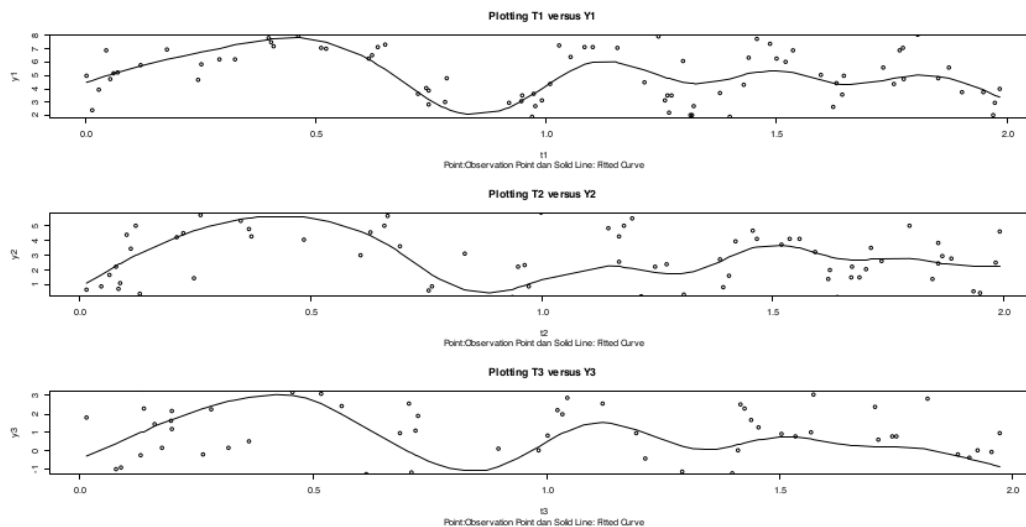


Figure 4. Plots of estimation of the first response (above), the second response (central), and the third response (below) of model (23) for great lambda, $\lambda = 1e-05$.

estimator, \hat{f}_{λ} , is an estimator which is linear in observations, and by taking expectation, $E(\hat{f}_{\lambda})$, it is a bias estimator for f . We can investigate the asymptotic properties of spline estimator (\hat{f}_{λ}) of regression function (f) by decomposing $IMSE(\hat{f}_{\lambda})$ into two components, i.e., $bias^2(\hat{f}_{\lambda})$ and $Var(\hat{f}_{\lambda})$, and the result has been given in (22).

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PAGE 7

PAGE 8

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PAGE 10

PAGE 11

PAGE 12

PAGE 13

PAGE 14

PAGE 15

PAGE 16
