

DAFTAR PUSTAKA

- Das, S., Gupta, P.K. 2011. A Mathematical Model on Fractional Lotka Volterra Equations, *Jurnal of Theoretical Biology*, vol.277, 1-6.
- Derouic, M., Boutayeb, A. 2006. Dengue fever:mathematical modelling and computer simulation. *Applied Mathematics and Computatio*. 177(2):528-544.
- El-Saka, H., El-Sayed, A. 2013. *Fractional Order Equations and Dynamical Systems*. Lambert Academic Publishing, Germany.
- Hemeda, A. A. 2012. *Metode Perturbasi Homotopi for Solving Partial Differential Equations of Fractional Order*, Int. Journal of Math. Analysis, Vol. 6, 2012, no.49, 2431-2448.
- Liu, Y., Xin, B. 2011. Numerical Solutions of a Fraksional Pemangsa Mangsa System. *Hindawi Publishing Corporation Advances in Difference Equations, Volume 2011*.
- Podlubny, I. 1999. *Fractional Differential Equations*. Academic Press.
- Pongsumpun, P., Tang, I. 2001. *A realistic age structured transmission model for dengue hemorrhagic fever in Thailand: Mhatematical and Computer Modelling*.

Side, S., Noorani, S. M. *A SIR Model for Spread of Dengue Fever Disease (Simulation for South Sulawesi, Indonesia and Selangor, Malaysia)*. World Journal of Modelling and Simulation. England, UK.

Sweilam, N. H., Khader, M. M., Mahdy A. M. S. 2012. Numerical Studies for Solving Fractional-Order Logistic Equation, Faculty of Science, Cairo University, *International Journal of Pure and Applied Mathematics vol.78, 1199-1210*.

WHO. Fact sheets: Dengue and Severe Dengue, 2014.
[Http://www.who.int/mediacentre/factsheets/fs117/en/](http://www.who.int/mediacentre/factsheets/fs117/en/).

W.O. Kermack, A.G. McKendrick. 1927. *A Contribution to the Mathematical Theory of Epidemics*. Proc. Roy. Soc. London.

Zill, D. G., Cullen, M. R., 2009. *Differential Equations with Boundary Value Problems Serventh Edition*.

Lampiran 1. Persamaan differensial fraksional $y_0, z_0, y_1, z_1, y_2, z_2, \dots$

Penentuan persamaan differensial fraksional untuk y_0, y_1, y_2, \dots dengan melakukan substitusi pada persamaan (4.3b) dari persamaan (4.4a)-(4.4c)

$$D^\beta(y_0 + py_1 + p^2y_2 + p^3y_3 + p^4y_4 + p^5y_5 + p^6y_6 + \dots) =$$

$$p[a(x_0 + px_1 + p^2x_2 + p^3x_3 + p^4x_4 + p^5x_5 + \dots)$$

$$(z_0 + pz_1 + p^2z_2 + p^3z_3 + p^4z_4 + p^5z_5 + \dots)$$

$$-b(y_0 + py_1 + p^2y_2 + p^3y_3 + p^4y_4 + p^5y_5 + \dots)]$$

$$D^\beta y_0 + pD^\beta y_1 + p^2D^\beta y_2 + p^3D^\beta y_3 + p^4D^\beta y_4 + p^5D^\beta y_5 + p^6D^\beta y_6 + \dots =$$

$$p[(ax_0z_0 + pax_0z_1 + p^2ax_0z_2 + p^3ax_0z_3 + p^4ax_0z_4 + p^5ax_0z_5 + \dots)$$

$$+ (pax_1z_0 + p^2ax_1z_1 + p^3ax_1z_2 + p^4ax_1z_3 + p^5ax_1z_4 + \dots) + (p^2ax_2z_0$$

$$+ p^3ax_2z_1 + p^4ax_2z_2 + p^5ax_2z_3 + \dots) + (p^3ax_3z_0 + p^4ax_3z_1 + p^5ax_3z_2$$

$$+ \dots) + (p^4ax_4z_0 + p^5ax_4z_1 + \dots) + (p^5ax_5z_0 + \dots) + \dots) - (by_0$$

$$+ pby_1 + p^2by_2 + p^3by_3 + p^4by_4 + p^5by_5 + \dots)]$$

$$D^\beta y_0 + pD^\beta y_1 + p^2D^\beta y_2 + p^3D^\beta y_3 + p^4D^\beta y_4 + p^5D^\beta y_5 + p^6D^\beta y_6 + \dots =$$

$$p(ax_0z_0 - by_0) + p^2(ax_0z_1 + ax_1z_0 - by_1) + p^3(ax_0z_2 + ax_1z_1 + ax_2z_0$$

$$- by_2) + p^4(ax_0z_3 + ax_1z_2 + ax_2z_1 + ax_3z_0 - by_3) + p^5(ax_0z_4 + ax_1z_3$$

$$+ ax_2z_2 + ax_3z_1 + ax_4z_0 - by_4) + p^6(ax_0z_5 + ax_1z_4 + ax_2z_3 + ax_3z_2$$

$$+ax_4z_1 + ax_5z_0 - by_5) + \dots$$

Penentuan persamaan differensial fraksional untuk z_0, z_1, z_2, \dots dengan melakukan substitusi pada persamaan (4.3c) dari persamaan (4.4a)-(4.4c)

$$\begin{aligned} D^\gamma(z_0 + pz_1 + p^2z_2 + p^3z_3 + p^4z_4 + p^5z_5 + p^6z_6 + \dots) &= p[c(y_0 + py_1 \\ &+ p^2y_2 + p^3y_3 + p^4y_4 + p^5y_5 + \dots) - c(z_0 + pz_1 + p^2z_2 + p^3z_3 + p^4z_4 \\ &+ p^5z_5 + \dots)(y_0 + py_1 + p^2y_2 + p^3y_3 + p^4y_4 + p^5y_5 + \dots) - \delta(z_0 + pz_1 \\ &+ p^2z_2 + p^3z_3 + p^4z_4 + p^5z_5 + \dots)] \end{aligned}$$

$$\begin{aligned} D^\gamma z_0 + pD^\gamma z_1 + p^2D^\gamma z_2 + p^3D^\gamma z_3 + p^4D^\gamma z_4 + p^5D^\gamma z_5 + p^6D^\gamma z_6 + \dots &= p[(cy_0 \\ &+ pcy_1 + p^2cy_2 + p^3cy_3 + p^4cy_4 + p^5cy_5 + \dots) - ((cz_0y_0 + pcz_0y_1 \\ &+ p^2cz_0y_2 + p^3cz_0y_3 + p^4cz_0y_4 + p^5cz_0y_5 + \dots) + (pcz_1y_0 + p^2cz_1y_1 \\ &+ p^3cz_1y_2 + p^4cz_1y_3 + p^5cz_1y_4 + \dots) + (p^2cz_2y_0 + p^3cz_2y_1 + p^4cz_2y_2 \\ &+ p^5cz_2y_3 + \dots) + (p^3cz_3y_0 + p^4cz_3y_1 + p^5cz_3y_2 + \dots) + (p^4cz_4y_0 \\ &+ p^5cz_4y_1 + \dots) + (p^5cz_5y_0 + \dots) + \dots) - (\delta z_0 + p\delta z_1 + p^2\delta z_2 + p^3\delta z_3 \\ &+ p^4\delta z_4 + p^5\delta z_5 + \dots)] \end{aligned}$$

$$\begin{aligned} D^\gamma z_0 + pD^\gamma z_1 + p^2D^\gamma z_2 + p^3D^\gamma z_3 + p^4D^\gamma z_4 + p^5D^\gamma z_5 + p^6D^\gamma z_6 + \dots &= p(cy_0 \\ &- cz_0y_0 - \delta z_0) + p^2(cy_1 - cz_0y_1 - cz_1y_0 - \delta z_1) + p^3(cy_2 - cz_0y_2 \\ &- cz_1y_1 - cz_2y_0 - \delta z_2) + p^4(cy_3 - cz_0y_3 - cz_1y_2 - cz_2y_1 - cz_3y_0 - \delta z_3) \end{aligned}$$

$$+p^5(cy_4 - cz_0y_4 - cz_1y_3 - cz_2y_2 - cz_3y_1 - cz_4y_0 - \delta z_4) + p^6(cy_5$$
$$- cz_0y_5 - cz_1y_4 - cz_2y_3 - cz_3y_2 - cz_4y_1 - cz_5y_0 - \delta z_5) + \dots$$

