

# Expansion of Ceva Theorem in the Normed Space with the Angle of Wilson

*by* Eridani Eridani

---

**Submission date:** 14-Dec-2018 04:55PM (UTC+0800)

**Submission ID:** 1056964192

**File name:** ART\_20179485,\_Journal.pdf (307.26K)

**Word count:** 1405

**Character count:** 5565

# Expansion of Ceva Theorem in the Normed Space with the Angle of Wilson

Muhammad Zakir<sup>1</sup>, Eridani<sup>2</sup>, Fatmawati<sup>3</sup>

<sup>1</sup>Department of Mathematics, Hasanuddin University, Indonesia

<sup>2,3</sup>Department of Mathematics, Airlangga University, Indonesia

**Abstract:** This paper discusses the expansion of Ceva theorem in the normed space. The Ceva theorem is expanded using the Wilson angle. Before entering the core issue first discusses about Wilson's angle and its properties. Furthermore, it is proved by the Ceva's Theorem by first modifying it.

**Keywords:** Ceva's Theorem, normed space, Wilson angle

## 1. Introduction

The angle between two vectors in the Euclidean space  $\mathbb{R}^2$  has been well known. In the Euclidean space the angle between two vectors is defined using the dot product [8]. An angle between two vectors has also been expanded in the inner product space [7]. Furthermore, in the normed space it has also been known the angle between the two vectors among other angles P, I, g ([1], [2], [3], [4]), Thy angle [2] and Wilson angle [6].

The angle in the normed space discussed in this paper is the angle of Wilson. The Wilson angle is introduced by Valentine and Wayment (1971). A review of the Wilson angle is discussed as follows :

Let  $(V, \|\cdot\|)$  be a normed space over the field  $\mathbb{R}$ , for any  $a, b \in V$  Defines a nonlinear function :

$$2\langle a, b \rangle := \|a\|^2 + \|b\|^2 - \|a-b\|^2 \quad (1)$$

From the nature of the normed space belongs :

$$\begin{aligned} \|a\| - \|b\| &\leq \|a-b\| \\ \Leftrightarrow \|a\|^2 - 2\|a\| \cdot \|b\| + \|b\|^2 &\leq \|a-b\|^2 \\ \Leftrightarrow \langle a, b \rangle &\leq \|a\| \cdot \|b\| \end{aligned} \quad (2)$$

meanwhile :

$$\begin{aligned} \|a-b\| &\leq (\|a\| + \|b\|) \\ \Leftrightarrow \|a-b\|^2 - \|a\|^2 - \|b\|^2 &\leq 2\|a\| \cdot \|b\| \\ \Leftrightarrow -\langle a, b \rangle &\leq \|a\| \cdot \|b\| \end{aligned} \quad (3)$$

Of the equation (2) and (3) obtained :

$$|\langle a, b \rangle| \leq \|a\| \cdot \|b\|, \quad \forall a, b \in V \quad (4)$$

fulfill the cauchy - Schwarz inequality [8]. The Wilson angle is defined as the angle between two vectors  $a$  and  $b$  satisfy

$$\angle(a, b) := \arccos \left( \frac{\|a\|^2 + \|b\|^2 - \|a-b\|^2}{2\|a\| \cdot \|b\|} \right) \quad (5)$$

From the angle of Wilson obtained the rules of cosine :

$$\|c\|^2 = \|a\|^2 + \|b\|^2 - 2\|a\| \cdot \|b\| \cos \angle(a, b) \quad (6)$$

Next from the equation (6) sine rules are obtained :

$$\|a\| \cdot \|b\| \sin \angle(a, b) = K \quad (7)$$

With  $K = 2\sqrt{s(s-\|a\|)(s-\|b\|)(s-\|c\|)}$  and

$$2s = \|a\| + \|b\| + \|c\|$$

## 2. Main Result

**Definition. 2.1.** Let  $(V, \|\cdot\|)$  be a normed space for  $a, b, c \in V \setminus \{0\}$ , defined  $\Delta[a, b, c]$  as  $\{a, b, c\}$  satisfy  $a+c=b$ , which completed with a Wilson angle  $\angle(a, b)$ ,  $\angle(-a, c)$ , dan  $\angle(b, c)$ .

**Definition. 2.2.** Let  $(V, \|\cdot\|)$  be a normed space for  $d \in V \setminus \{0\}$ , called the Ceva vector of  $\Delta[a_1, a_2, a_3]$  if any  $\alpha \in (0, 1)$  so that it satisfies  $\alpha a_i + d = a_j$  with  $i \neq j$ .

**Definition. 2.3.** Let  $(V, \|\cdot\|)$  be a normed space for  $d, e, f \in V \setminus \{0\}$ , called vector ceva ally of  $\Delta[a, b, c]$  if any  $\alpha_i \in (0, 1)$ ,  $i=1,2,3,4,5,6$  so that it satisfies  $(1-\alpha_6)f+a=(1-\alpha_5)e$ ,  $(1-\alpha_5)e+c=(1-\alpha_4)d$ ,  $(1-\alpha_6)f+b=(1-\alpha_4)d$

Theorem. 2.1. Let  $(V, \|\cdot\|)$  be a normed space for  $\Delta[(1-\alpha_6)f, (1-\alpha_5)e, a]$  with angle  $\angle(-a, (1-\alpha_6)f)$ ,  $\angle((1-\alpha_5)e, (1-\alpha_6)f)$  and  $\angle(a, (1-\alpha_5)e)$  obtained :

1. Let  $d, e, f \in V \setminus \{0\}$  be a so that it satisfies

$$\begin{aligned} (1-\alpha_6)f + a &= (1-\alpha_5)e, \\ (1-\alpha_5)e + c &= (1-\alpha_4)d, \\ (1-\alpha_6)f + b &= (1-\alpha_4)d, \quad \text{with } \alpha_i \in (0,1), \\ \text{and } i &= 1,2,3,4,5,6 \end{aligned}$$

$$2. \frac{\sin \angle(-b, (1-\alpha_6)f) \cdot \sin \angle(c, (1-\alpha_4)d)}{\sin \angle(b, (1-\alpha_4)d) \cdot \sin \angle(-c, (1-\alpha_5)e)} \cdot \frac{\sin \angle(a, (1-\alpha_5)e)}{\sin \angle(-a, (1-\alpha_6)f)} = 1$$

$$3. \frac{\|(1-\alpha_1)a\| \cdot \|(1-\alpha_3)c\| \cdot \|(1-\alpha_2)b\|}{\|(1-\alpha_1)a\| \cdot \|(1-\alpha_3)c\| \cdot \|(1-\alpha_2)b\|} = 1$$

Proof.

(1  $\Rightarrow$  2)

pay attention  $\Delta[(1-\alpha_6)f, (1-\alpha_4)d, b]$  with angle  $\angle(-b, (1-\alpha_6)f)$ ,  $\angle((1-\alpha_6)f, (1-\alpha_4)d)$  and  $\angle(b, (1-\alpha_4)d)$  obtained :

$$K_1 = \|-b\| \cdot \|(1-\alpha_6)f\| \sin \angle(-b, (1-\alpha_6)f) \quad (8)$$

$$K_1 = \|b\| \cdot \|(1-\alpha_4)d\| \sin \angle(b, (1-\alpha_4)d) \quad (9)$$

From equation (8) dan (9) obtained :

$$\begin{aligned} \frac{\sin \angle(-b, (1-\alpha_6)f)}{\sin \angle(b, (1-\alpha_4)d)} &= \frac{\|b\| \cdot \|(1-\alpha_4)d\|}{\|-b\| \cdot \|(1-\alpha_6)f\|} \\ &= \frac{\|(1-\alpha_4)d\|}{\|(1-\alpha_6)f\|} \quad (10) \end{aligned}$$

pay attention  $\Delta[(1-\alpha_5)e, (1-\alpha_4)d, c]$  with angle  $\angle(-c, (1-\alpha_5)e)$ ,  $\angle((1-\alpha_5)e, (1-\alpha_4)d)$  and  $\angle(c, (1-\alpha_4)d)$ . Obtained :

$$K_2 = \|c\| \cdot \|(1-\alpha_4)d\| \sin \angle(c, (1-\alpha_4)d) \quad (11)$$

$$K_2 = \|-c\| \cdot \|(1-\alpha_5)e\| \sin \angle(-c, (1-\alpha_5)e) \quad (12)$$

From equation (11) and (12) obtained :

$$\begin{aligned} \frac{\sin \angle(c, (1-\alpha_4)d)}{\sin \angle(-c, (1-\alpha_5)e)} &= \frac{\|-c\| \cdot \|(1-\alpha_5)e\|}{\|c\| \cdot \|(1-\alpha_4)d\|} \\ &= \frac{\|(1-\alpha_5)e\|}{\|(1-\alpha_4)d\|} \quad (13) \end{aligned}$$

$\Delta[(1-\alpha_6)f, (1-\alpha_5)e, a]$  with angle  $\angle(-a, (1-\alpha_6)f)$ ,  $\angle((1-\alpha_5)e, (1-\alpha_6)f)$  and  $\angle(a, (1-\alpha_5)e)$  obtained :

$$K_3 = \|-a\| \cdot \|(1-\alpha_6)f\| \sin \angle(-a, (1-\alpha_6)f) \quad (14)$$

$$K_3 = \|a\| \cdot \|(1-\alpha_5)e\| \sin \angle(a, (1-\alpha_5)e) \quad (15)$$

From equation (14) and (15) obtained :

$$\begin{aligned} \frac{\sin \angle(a, (1-\alpha_5)e)}{\sin \angle(-a, (1-\alpha_6)f)} &= \frac{\|-a\| \cdot \|(1-\alpha_6)f\|}{\|a\| \cdot \|(1-\alpha_5)e\|} \\ &= \frac{\|(1-\alpha_6)f\|}{\|(1-\alpha_5)e\|} \quad (16) \end{aligned}$$

Multiply equations (10), (13) and (16) then obtained :

$$\begin{aligned} \frac{\sin \angle(-b, (1-\alpha_6)f) \cdot \sin \angle(c, (1-\alpha_4)d)}{\sin \angle(b, (1-\alpha_4)d) \cdot \sin \angle(-c, (1-\alpha_5)e)} \cdot \frac{\sin \angle(a, (1-\alpha_5)e)}{\sin \angle(-a, (1-\alpha_6)f)} &= \frac{\|(1-\alpha_4)d\|}{\|(1-\alpha_6)f\|} \\ &\cdot \frac{\|(1-\alpha_5)e\| \cdot \|(1-\alpha_6)f\|}{\|(1-\alpha_4)d\| \cdot \|(1-\alpha_5)e\|} = 1 \end{aligned}$$

(2  $\Rightarrow$  3)

$$\begin{aligned} \frac{\sin \angle(a, (1-\alpha_5)e)}{\sin \angle(-a, (1-\alpha_6)f)} \cdot \frac{\sin \angle(-b, (1-\alpha_6)f)}{\sin \angle(b, (1-\alpha_4)d)} &= \frac{\sin \angle(c, (1-\alpha_4)d)}{\sin \angle(-c, (1-\alpha_5)e)} = 1 \\ \frac{\sin \angle(-\alpha_2 b, (1-\alpha_6)f)}{\sin \angle(-\alpha_1 a, (1-\alpha_6)f)} &= \frac{\sin \angle((1-\alpha_1)a, (1-\alpha_5)e)}{\sin \angle(-\alpha_3 c, (1-\alpha_5)e)} \\ &\cdot \frac{\sin \angle((1-\alpha_3)c, (1-\alpha_4)d)}{\sin \angle((1-\alpha_4)d, (1-\alpha_2)b)} = 1 \end{aligned}$$

$$\Leftrightarrow \frac{K_2}{\|- \alpha_2 b\| \cdot \|(1-\alpha_6)f\|} \cdot \frac{K_1}{\|-\alpha_1 a\| \cdot \|(1-\alpha_6)f\|}$$

$$\Leftrightarrow \frac{K_1}{\|(1-\alpha_1)a\| \cdot \|(1-\alpha_5)e\|} \cdot \frac{K_3}{\|-\alpha_3 c\| \cdot \|(1-\alpha_5)e\|}$$

$$\frac{K_3}{\|(1-\alpha_3)c\| \cdot \|(1-\alpha_4)d\|} = 1$$

$$\frac{K_2}{\|(1-\alpha_4)d\| \cdot \|(1-\alpha_2)b\|}$$

$$\Leftrightarrow \frac{\|-\alpha_1a\|}{\|(1-\alpha_1)a\|} \cdot \frac{\|-\alpha_3c\|}{\|(1-\alpha_3)c\|} \cdot \frac{\|(1-\alpha_2)b\|}{\|-\alpha_2b\|} = 1$$

(3  $\Rightarrow$  1)

Suppose that  $(1-\alpha_6)f + a \neq (1-\alpha_4)e$

For example  $(1-\alpha_6)f + a = \beta g$  then

$$\frac{\|-\alpha_1a\|}{\|(1-\alpha_1)a\|} \cdot \frac{\|\beta c\|}{\|(1-\beta)c\|} \cdot \frac{\|(1-\alpha_2)b\|}{\|-\alpha_2b\|} = 1 \quad (17)$$

While it is known :

$$\frac{\|-\alpha_1a\|}{\|(1-\alpha_1)a\|} \cdot \frac{\|-\alpha_3c\|}{\|(1-\alpha_3)c\|} \cdot \frac{\|(1-\alpha_2)b\|}{\|-\alpha_2b\|} = 1 \quad (18)$$

From equation (15) and (16) obtained :

$$\frac{\|\beta c\|}{\|(1-\beta)c\|} = \frac{\|-\alpha_3c\|}{\|(1-\alpha_3)c\|} \quad (19)$$

$$\alpha_3 = \beta \quad \text{or} \quad f = g$$

## References

- [1] Gunawan H, Lindiami J, Neswan O, 2008. P, I, g and D Angles in Norm Space, *ITB, J Sci*, Vol 40A No.1; 24 – 32.
- [2] Milicic, P.M, 2011. The Thy-Angle and g-Angle in a Quasi-Inner Product Space, *Mathematica Moravica*, Vol. 15-2; 41 – 46.
- [3] Milicic, P.M, 2011. Singer Orthogonality and James Orthogonality in the So-Called Quasi-Inner Product Space, *Mathematica Moravica*, Vol. 15-1; 49 – 52.
- [4] Milicic, P.M, 2007. On the B-Angle and g-angle in Normed Space, *Journal of Inequalities in Pure and Applied Mathematics*, Vol. 8, issue 3, article 99, 9pp.
- [5] Milicic, P.M, 2002. On Moduli of the duality Mapping of smooth Banach Space, *Journal of inequalities in pure and applied Mathematics*; Vol. 2, issue 4, article 51, 15pp.
- [6] Valentine., and Wayment. 1971. Wilson Angles in Linear Normed Space . *Pacific Journal of Mathematics* , Vol. 36, No.1, 239 – 243.
- [7] Anton H, 2010, Elementary Linear Algebra , 10<sup>rd</sup> Edition, John Wiley & Sons
- [8] Bottema O, 2008, Topics in Elementtary Geometry, 2<sup>rd</sup> Edition, Springer Science Business Media,LLC

# Expansion of Ceva Theorem in the Normed Space with the Angle of Wilson

## ORIGINALITY REPORT

20%

SIMILARITY INDEX

19%

INTERNET SOURCES

14%

PUBLICATIONS

0%

STUDENT PAPERS

## PRIMARY SOURCES

1

[documents.mx](https://documents.mx)

Internet Source

7%

2

[pastebin.com](https://pastebin.com)

Internet Source

3%

3

[digitalage.hu](https://digitalage.hu)

Internet Source

1%

4

[www.fq.math.ca](http://www.fq.math.ca)

Internet Source

1%

5

[chem4823.usask.ca](https://chem4823.usask.ca)

Internet Source

1%

6

[f3b.ru](https://f3b.ru)

Internet Source

1%

7

[www.dumar-zywiec.pl](http://www.dumar-zywiec.pl)

Internet Source

1%

8

[www.coursehero.com](http://www.coursehero.com)

Internet Source

1%

9

[echinaceaproject.org](https://echinaceaproject.org)

Internet Source

1%

10

[www.openmathtext.org](http://www.openmathtext.org)

Internet Source

1%

11

[tiktakdoc.com](http://tiktakdoc.com)

Internet Source

1%

12

Chen Gao, Karen Panetta, Sos Agaian. "A new color contrast enhancement algorithm for robotic applications", 2012 IEEE International Conference on Technologies for Practical Robot Applications (TePRA), 2012

Publication

1%

13

[mat.uniroma2.it](http://mat.uniroma2.it)

Internet Source

1%

14

Serge Lang. "Undergraduate Analysis", Springer Nature, 1983

Publication

1%

15

[edoc.site](http://edoc.site)

Internet Source

1%

Exclude quotes Off

Exclude matches Off

Exclude bibliography On

# Expansion of Ceva Theorem in the Normed Space with the Angle of Wilson

---

GRADEMARK REPORT

---

FINAL GRADE

**/0**

GENERAL COMMENTS

**Instructor**

---

PAGE 1

---

PAGE 2

---

PAGE 3

---